## High-order magneto-hydrodynamic code with spontaneous magnetic fields generation

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#### Abstract

The magneto-hydrodynamic description is adopted in many disciplines, where the dynamics of magnetized fluids is investigated. It plays a vital role in plasma physics, where high-temperature plasma becomes highly electrically conductive. Its modelling is then essential for the applications like inertial and magnetic confinement fusion, laboratory astrophysics and many others. For this purpose, we recently developed the resistive magneto-hydrodynamic extension of the multi-dimensional simulation code PETE2 (Plasma Euler and Transport Equations version 2) [1, 2]. The Lagrangian nature of the code means that the computational mesh follows the flow of the matter unlike the traditional codes. Its numerical description is based on the high-order curvilinear finite elements, which provide high precision, computing efficiency, flexibility and robustness. The latest addition is the model of spontaneous magnetic fields, which are generated during the laser–target interaction or at the fronts of cosmic jets and elsewhere. The construction of the code is reviewed and examples of physically relevant simulations are given.

#### **Objectives:**

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#### Examples

#### crossed gradients

• initial profiles of density and temperature:

$$\rho_0(x,y) = 1 + 10^{-3}(\cos(\pi x) + \cos(\pi y) + \cos(\pi z))$$
  
$$T_0(x,y) = 100 + 10^{-1}(\cos(\pi x) + \sin(\pi y) + \cos(\pi z))$$

• analytic solution for the linear regime ( $t = 10^{-20}$  s)

• random mesh (20 %) – 2nd order  $\mathcal{T}, \mathcal{M}, \mathcal{D}$ , 3rd order  $\mathcal{K}, \mathcal{E}, \mathcal{G}$  finite elements



- two-temperature resistive Lagrangian MHD
- high-order curvilinear finite element discretization
- identification and curing of the Biermann catastrophe on shock fronts
- high-order Biermann battery discretization

#### Lagrangian resistive MHD:

- magnetized fluid in a magnetic field
- resistive electric currents  $\vec{j} = \eta^{-1}\vec{E}$  ( $\vec{E}$  fluid-frame electric field,  $\eta$  resistivity)
- closure model for the stress tensor  $\overline{\overline{\sigma}} = -p\overline{\overline{I}}$
- magnetic stress tensor  $\overline{\overline{\sigma}}_B = 1/\mu_0 (\vec{B}\vec{B} \frac{1}{2}\vec{B^2}\overline{\overline{I}})$
- magnetic energy  $\epsilon_B = \vec{B}^2/(2\mu_0)$  (in the rest frame)

mass conservation	$\frac{\mathrm{d}\rho}{\mathrm{d}t} = -\rho\nabla\cdot\vec{u}$
momentum conservation	$\rho \frac{\mathrm{d}\vec{u}}{\mathrm{d}t} = \nabla \cdot (\overline{\overline{\sigma}} + \overline{\overline{\sigma}}_B)$
Faraday's law	$\frac{\mathrm{d}\vec{B}}{\mathrm{d}t} = -\nabla \times \vec{E}$
internal energy conservation	$\rho \frac{\mathrm{d}\varepsilon}{\mathrm{d}t} = \overline{\overline{\sigma}} : \nabla \vec{u} + \vec{j} \cdot \vec{E}$
magnetic energy conservation	$\frac{\mathrm{d}\epsilon_B}{\mathrm{d}t} = \overline{\overline{\sigma}}_B : \nabla \vec{u} - \frac{1}{\mu_0} \vec{B} \cdot \nabla \times \vec{E}$

- ( $\rho$  mass density,  $\vec{u}$  velocity,  $\varepsilon$  specific internal en.,  $\varepsilon_B$  specific mag. en., p pressure) **curvilinear high-order MHD[1]:**
- high-order finite elements  $\Rightarrow$  computational efficiency, mesh design flexibility
- $\bullet$  curvilinear isoparametric finite elements  $\Rightarrow$  tracking of interfaces and discontinuities
- mass, momentum and energy conserving
- divergence-free magnetic field
- extended to the two-temperature model[2] for the Biermann battery simulations

functional space name	$1D (\parallel / \perp)$	$2D (\parallel / \perp)$	3D
thermodynamic ( $\mathcal{T}$ )		$L_2$	
kinematic ( $\mathcal{K}$ )	$(H^{1})^{1}$	$(H^{1})^{2}$	$(H^{1})^{3}$
magnetic field ( $\mathcal{M}$ )	$L_2/(L_2)^2$	$H_{div}/L_2$	$H_{div}$
electric field ( $\mathcal{E}$ )	$-/(H^1)^2$	$H_{curl}/H^1$	$H_{curl}$

#### **Biermann battery**

• electron momentum eq.  $\Rightarrow$  el. field  $\vec{E}_B$  to maintain quasi-neutrality = *Biermann term* 

$$n_e m_e \frac{\partial \vec{u}_e}{\partial \vec{u}_e} = 0 = -\nabla p_e - n_e e \vec{E}_B$$

magn. of magnetic field [statT] ( $20 \times 20$  el.)

magn. of magnetic field [statT] ( $8 \times 8 \times 8$  el.)

#### ellipsoidal blast wave

- Sedov blast problem for t < 0.4 s high energy placed in the center ( $e_0 = 1 \text{ erg}$ )  $\Rightarrow$  spherical blast wave to the cold medium ( $\gamma = 5/3$ ,  $\rho_0 = 1 \text{ g/cm}^3$ , A = 1, Z = 1)
- domain  $\Omega = (-1.5, +1.5) \times (-1.5, +1.5) \text{ cm}$
- prolongation of the profiles along the horizontal axis at t = 0.4 s by 50 %
- propagation of an ellipsoidal blast wave for  $0.4 \,\mathrm{s} < t \le 0.6 \,\mathrm{s}$
- heat conduction  $\kappa/(\rho c_{Ve}) \doteq 0.35 \,\mathrm{cm}^2/\mathrm{s} \Rightarrow$  crossed gradients of  $\rho$  and  $T_e \Rightarrow$  generation of  $\vec{B}$
- resistivity  $\eta/\mu_0 \doteq 0.018 \,\mathrm{cm}^2/\mathrm{s} \Rightarrow$  slow magnetic field diffusion
- $30 \times 30$  elements 2nd order T, M, D, 3rd order K, E, G finite elements



#### Conclusions

- Biermann battery term constructed for the high-order curvilinear Lagrangian MHD
- two formulations compared on the problem of an ellipsoidal blast wave
- smooth and convergent results obtained for the *dual form*
- $\Rightarrow$  high-order FE modelling provides high computational efficiency and flexibility
- $\Rightarrow$  enabled detailed simulations of shock-generated magnetic fields in ICF and astrophysics

#### **Forthcoming Research**

- generalization for a realistic equation-of-state of electrons
- extension of MHD by additional terms (Nernst effect, Righi-Leduc ...)
- parallelization and optimization for different architectures including IT4I infrastructure

$$\partial t$$

• *naive model* – direct discretization

$$\vec{E}_B = -\frac{\nabla p_e}{en_e}$$
 (pressure is not continuous over a shock front!)

• *dual form*[3] – ideal gas equation-of-state is assumed for  $p_e = n_e k_B T_e$  (note gradient parts do not contribute to  $\vec{B}$ )

$$\vec{E}_B = -\frac{k_B T_e}{e p_e} \nabla p_e = -\frac{k_B}{e} \nabla (T_e \ln p_e) + \frac{k_B \ln p_e}{e} \nabla T_e$$

• spontaneous magnetic field generation

$$\frac{\mathrm{d}\vec{B}}{\mathrm{d}t} = -\nabla \times \vec{E}_B = -\frac{\nabla n_e \times \nabla p_e}{en_e^2} = \frac{k_B}{\underline{e}} \nabla \ln p_e \times \nabla T_e$$

• weak formulation (with  $\mathcal{G}(\Omega) \subset H_{div}(\Omega)$ ,  $\mathcal{D} \subset L_2(\Omega)$ )  $\Rightarrow$  high-order FEM discretization

$$\int_{\Omega} \mathbf{g}_{\ln p_{e}} \cdot \vec{\xi} \, \mathrm{d}V = \oint_{\partial \Omega} \ln p_{e} \vec{\xi} \cdot \mathrm{d}\vec{S} - \int_{\Omega} \ln p_{e} \nabla \cdot \vec{\xi} \, \mathrm{d}V \qquad \forall \vec{\xi} \in \mathcal{G}(\Omega)$$

$$\int_{\Omega} \mathbf{g}_{T_{e}} \vec{\xi} \, \mathrm{d}V = \oint_{\partial \Omega} T_{e} \vec{\xi} \cdot \mathrm{d}\vec{S} - \int_{\Omega} T_{e} \nabla \cdot \vec{\xi} \, \mathrm{d}V \qquad \forall \vec{\xi} \in \mathcal{G}(\Omega)$$

$$\int_{\Omega} \frac{\mathrm{d}\mathbf{B}}{\mathrm{d}t} \cdot \vec{\Xi} \, \mathrm{d}V + \int_{\Omega} \alpha \nabla \cdot \vec{\Xi} \, \mathrm{d}V = \frac{k_{B}}{e} \int_{\Omega} \mathbf{g}_{\ln p_{e}} \times \mathbf{g}_{T_{e}} \cdot \vec{\Xi} \, \mathrm{d}V \qquad \forall \vec{\Xi} \in \mathcal{M}(\Omega)$$

$$\int_{\Omega} \nabla \cdot \mathbf{B} \mu \, \mathrm{d}V = 0 \qquad \forall \mu \in \mathcal{D}(\Omega)$$

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